

# Knight's Tour in $C_g$

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# Agenda

- 1 Introduction
- 2 Mapping
- 3 Results
- 4 Analysis

# Knight's Tour

- Ancient chess puzzle
- Visit every square **once**
- $\mathcal{NP}$  complete
- Open tour
  - Hamiltonian path
- Closed tour
  - Hamiltonian cycle

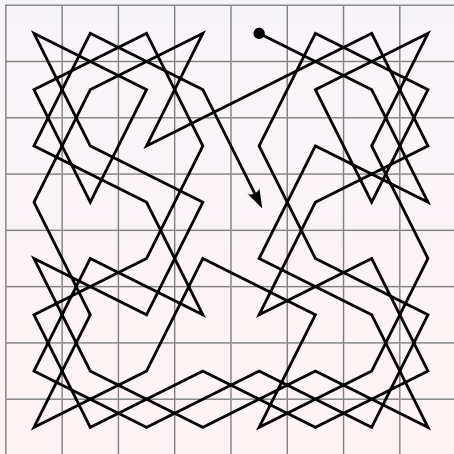


Figure: Courtesy of Ilmari Karonen [5]

# Naïve approach

- Depth-first search
- Backtrack from dead ends
- $O(8^n)$  time complexity

## Variations

- Visit neighbors **out of order**
- Try random permutations
- Look up precomputed solutions

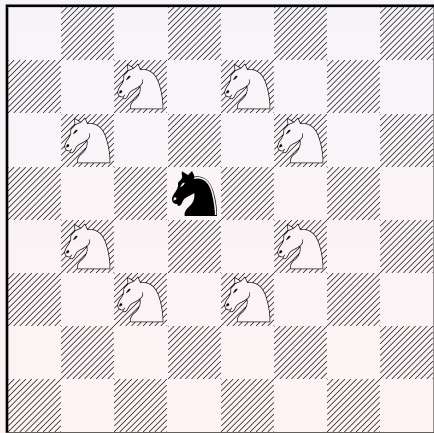


Figure: Possible moves for a knight.

# Warnsdorff's heuristic

- Visit **lowest** ranking neighbor
  - Ties do not matter
- Eliminates backtracking
- Works most of the time

## Definition

Rank — number of unvisited neighbors

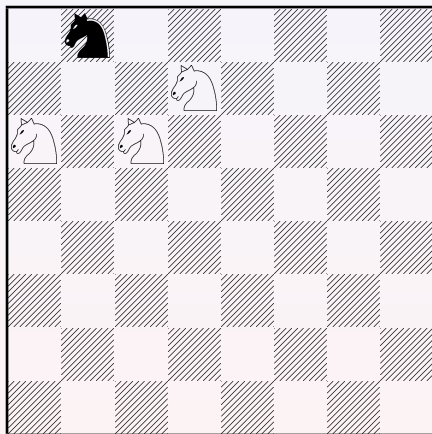


Figure: Which neighbor to visit first?

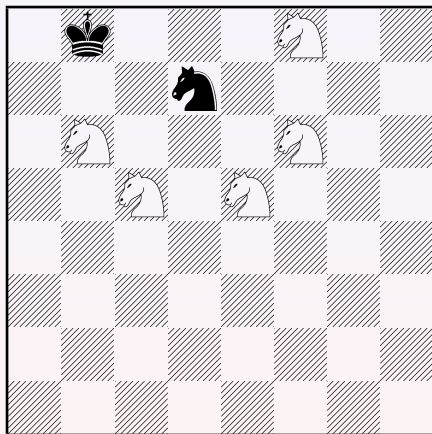


Figure: Right neighbor has rank 5.

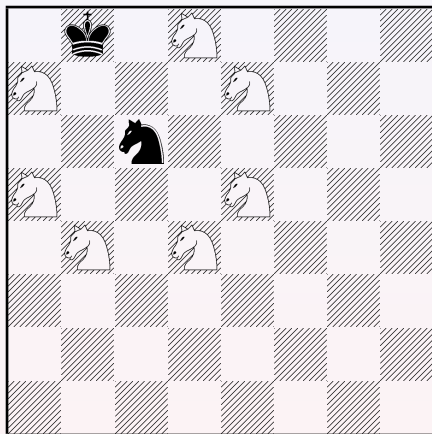


Figure: Middle neighbor has rank 7.



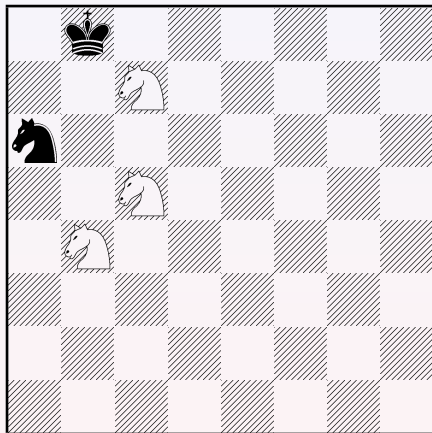


Figure: Left neighbor has rank 3.

# Further optimizations

- 2, 3,  $\dots$   $n$  square look ahead for Warnsdorff's heuristic
  - Tie arbitration
  - Multiple hops
- Parallel divide and conquer algorithms [2]
  - Divide board into 4 quadrants
  - Solve quadrants in parallel
  - Merge results together
- Genetic algorithms for tour discovery [3]

# Warnsdorff's heuristic in $C_g$

## Parallel

- All squares calculate own rank
  - Knight simply reads neighboring ranks
- All squares calculate next move
  - Only knight's calculation is trusted

## Sequential

- Only one knight is touring

# Moving the knight

## Problem

- Pixel shader's output position is fixed
- Cannot alter values of other pixels

## Solution

- Knight **indicates** next square in tour
- Next square pulls knight onto itself

# A knight's visit

## Cycle 1

- Knight arrives

## Cycle 2

- Neighboring ranks computed

## Cycle 3

- Next square computed
- Knight leaves

# Cycle 0

- Knight indicates next square
- Knight prepares for departure

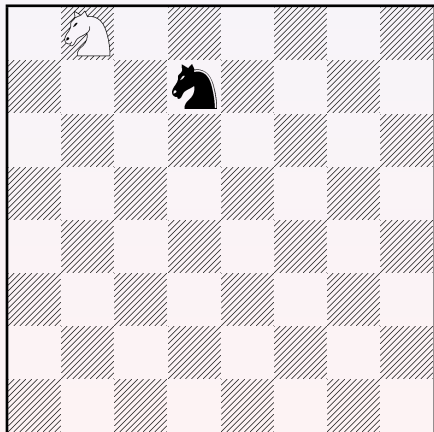


Figure: A knight's travel plans.

## Cycle 1

- Knight arrives
- Neighbors compute **wrong** rank

Figure: Previously...

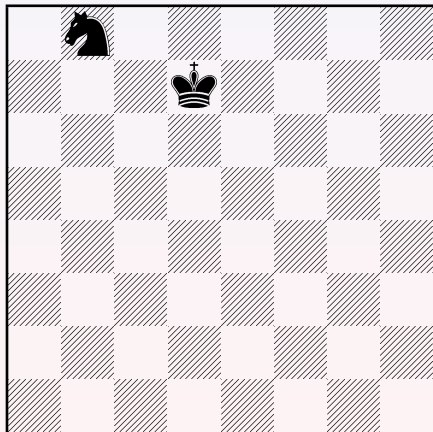
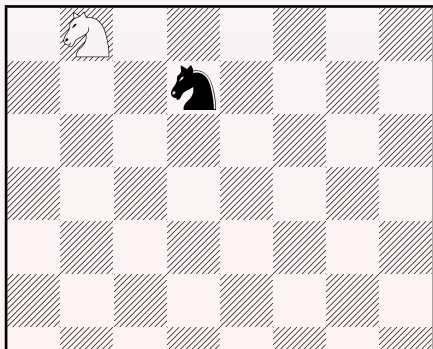


Figure: Unbeknown, a knight arrives.

## Cycle 2

- Neighbors acknowledge knight
- Neighbors compute correct rank

Figure: Previously...

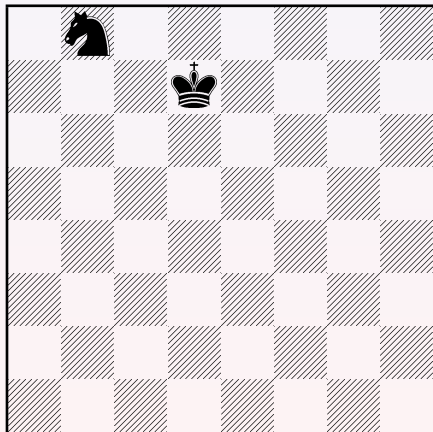
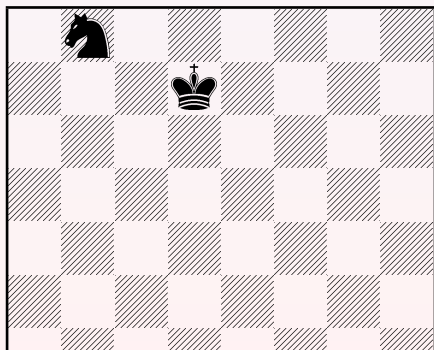


Figure: Hark! A knight be among us!



## Cycle 3

- Knight indicates next square
- Knight prepares for departure

Figure: Previously...

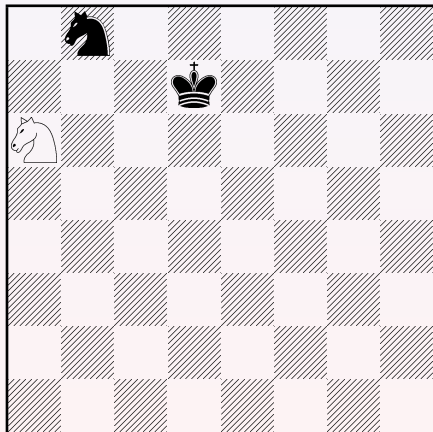
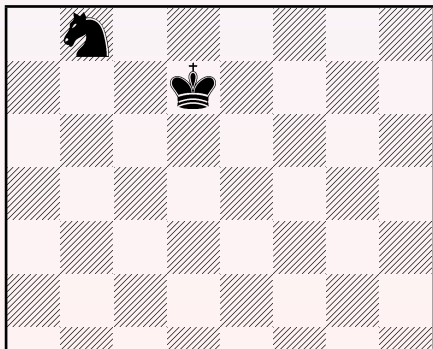


Figure: A knight's travel plans.

## Cycle 4

- The process continues

Figure: Previously...

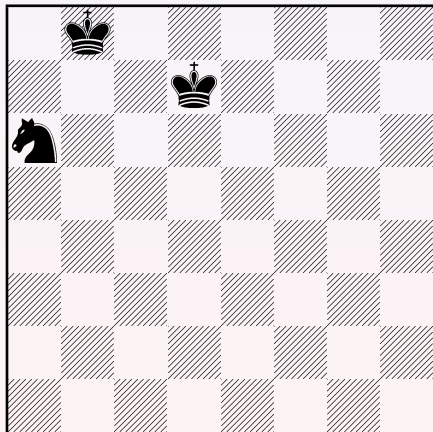
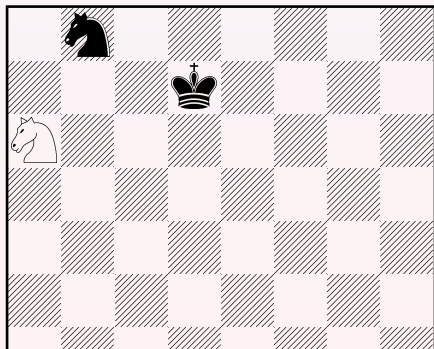


Figure: The tour continues, as before.

# Data structure

RGBA array of 32-bit floating point numbers

**Red** Counter for knight's visits  $1, 2, \dots, n$

**Green** Counter for knight's decision cycle

**Blue** Warnsdorff's rank at this square

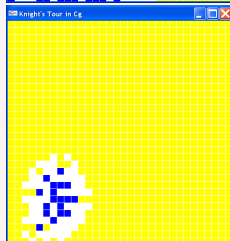
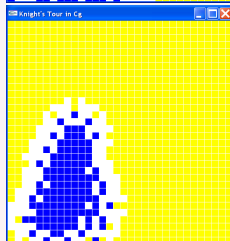
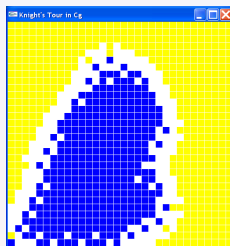
**Alpha** Knight's next move from this square

# Sample output

```
chess board's width?      8
knight's starting row?   2
knight's starting column? 4
```

The Knight toured in this order:

```
27 12 37 16 25  2 47 18
36 15 26 13 50 17 24  3
11 28 63 38  1 48 19 46
56 35 14 49 62 51  4 23
29 10 57 64 39 22 45 20
34 55 32 61 52 59 42  5
 9 30 53 58  7 40 21 44
54 33  8 31 60 43  6 41
```



chess board's width? 32  
knight's starting row? 9  
knight's starting column? 15

# Knight's decision with Warnsdorff's heuristic

- $\text{minRank} \leftarrow \infty$
- $\text{successor} \leftarrow \emptyset$
- for each neighbor do
  - $\text{rank} \leftarrow \text{neighbor's rank}$
  - if  $\text{rank} < \text{minRank}$ 
    - $\text{minRank} \leftarrow \text{rank}$
    - $\text{successor} \leftarrow \text{neighbor}$
  - end
- end

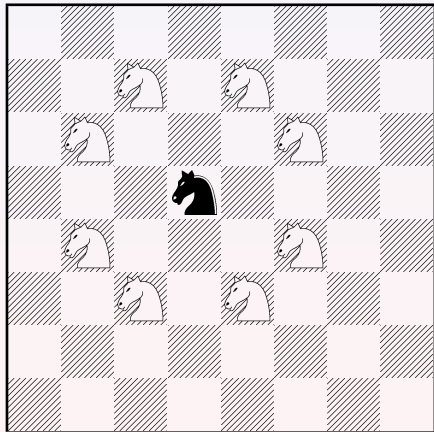


Figure: A knight and his neighbors.

# Tour duration with Warnsdorff's heuristic

$$\begin{aligned}
 CPU_{NextMove} &= 8_{neighbors} \times (1_{rank} \times 8_{neighbors} + 1_{minRank}) \\
 CPU_{duration} &= N_{knights} \times CPU_{NextMove} \times 1_{cycle} \\
 &= N_{knights} \times 72_{cycles}
 \end{aligned}$$

$$\begin{aligned}
 GPU_{NextMove} &= 8_{neighbors} \times (1_{rank} \times 0_{neighbors} + 1_{minRank}) \\
 GPU_{duration} &= N_{knights} \times GPU_{NextMove} \times 3_{cycles} \\
 &= N_{knights} \times 24_{cycles}
 \end{aligned}$$




# Speedup from parallelization of rank calculation

$$\begin{aligned} \text{speedup} &= \frac{CPU_{duration}}{GPU_{duration}} \\ &= \frac{N_{knights} \times 72_{cycles}}{N_{knights} \times 24_{cycles}} \\ &= 3 \end{aligned}$$



# Lessons learned

- OpenGL back buffer is RGBA8
  - Use FBO extension to preserve floats
- `GL_TEXTURE_RECTANGLE_ARB` does not fit to screen
  - Visualize data using `GL_TEXTURE_2D`
- `texRECT()` clamps out of bound indices
  - Check bounds beforehand
- Cg dislikes  $> 4$  nested loops
  - Unroll loops with code generation
  - eRuby (embedded Ruby) template

-  K. McGown, A. Leininger, and P. Cull, “Knight’s Tour”, 15 August 2002, [Article]. Available: [http://www.math.oregonstate.edu/~math\\_reu/Papers/Cull12-2002.pdf](http://www.math.oregonstate.edu/~math_reu/Papers/Cull12-2002.pdf). [Accessed: 17 March 2007].
-  I. Parberry, “An efficient algorithm for the Knight’s tour problem”, in *Discrete applied mathematics*, 1997, vol. 73, no. 3, pp. 251–260.
-  V. S. Gordon and T. J. Slocum, “The knight’s tour — evolutionary vs. depth-first search”, in Proc. *Congress on Evolutionary Computation*, 19–23 June 2004, vol. 2, pp. 1435–1440.



G. Törnberg, "Warndorff's rule", 1999, [Online document].

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[Accessed: 16 March 2007].



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[//en.wikipedia.org/wiki/Image:Knight%27s\\_tour.svg](http://en.wikipedia.org/wiki/Image:Knight%27s_tour.svg).

[Accessed: 20 March 2007].

# Questions?

Thanks for your attention.